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EVEREST+

RUN-TIME SLA VIOLATION PREDICTION



MW4SOC, Bagalore, 29/11/2010



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Outline

- Prediction approaches limitations
- Our vision
- EVEREST+
- Experimental results
- Conclusions





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Prediction approaches limitations

- They tend to **focus on system infrastructure properties** rather than service level application based properties.
- They tend to focus on the **prediction of specific types of properties** without providing a more generic framework for building predictors.
- They are **not integrated with environments for monitoring** SLAs for service-based systems.





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Our vision

- To focus on system infrastructure properties and **service level application based properties**.
- To provide a more **generic framework for building predictors** that can cover a wide or even the whole spectrum of service properties that can be part of an SLA
- To **integrate with environments for monitoring** SLAs for service-based systems





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EVEREST+

- EVEREST+ is a framework for integrated monitoring and prediction
- EVEREST+ uses prediction specifications to setup both the monitoring and the prediction framework
- EVEREST+ provides the means for developing new predictors





EVEREST+: architecture

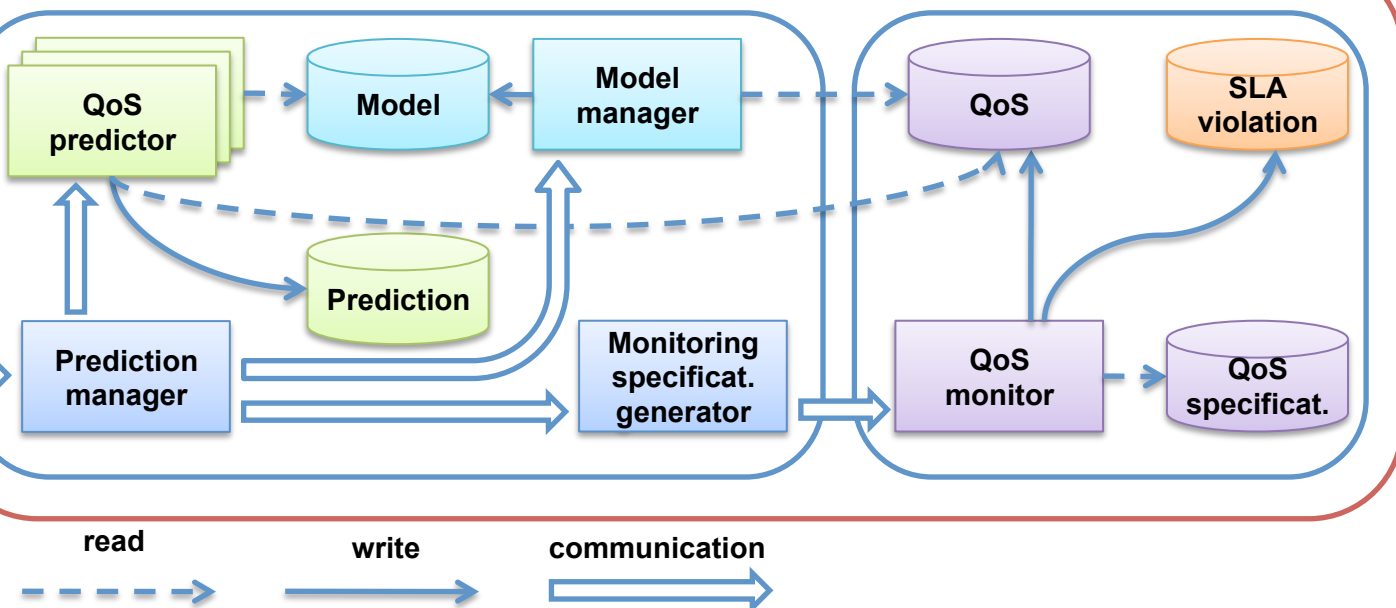
EVEREST+

Prediction Framework

EVEREST

Prediction specificat.

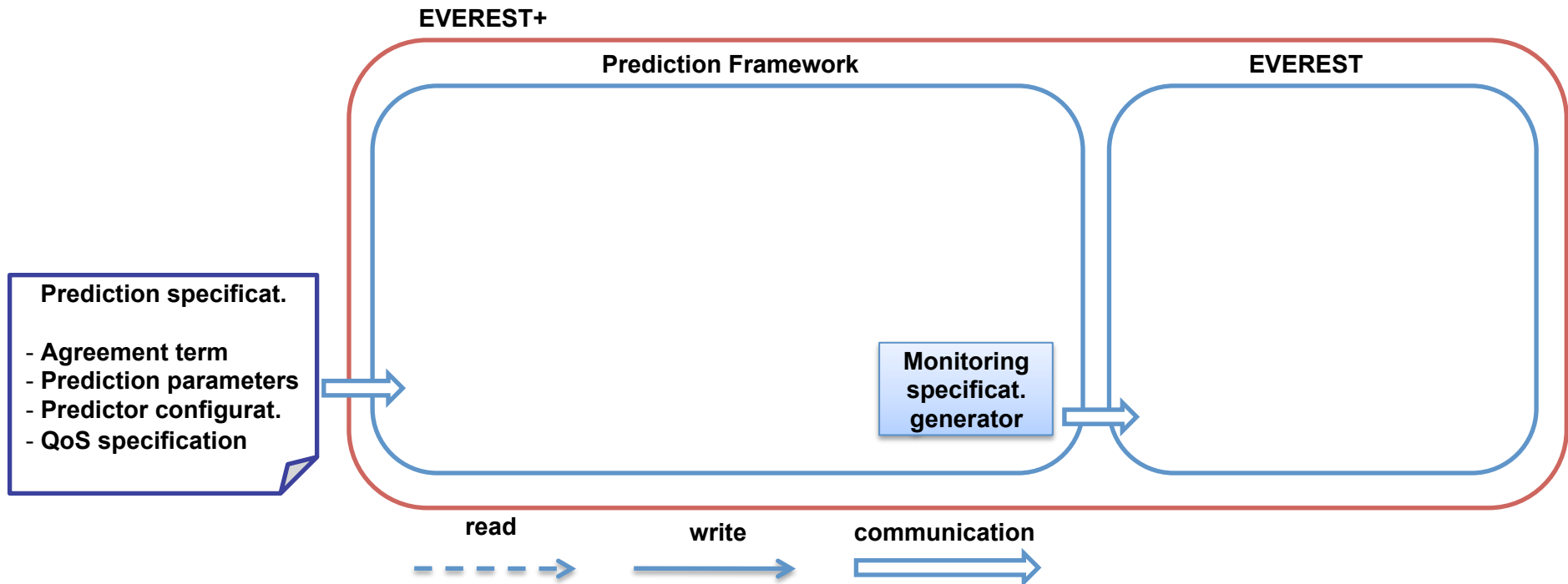
- Agreement term
- Prediction parameters
- Predictor configurat.
- QoS specification





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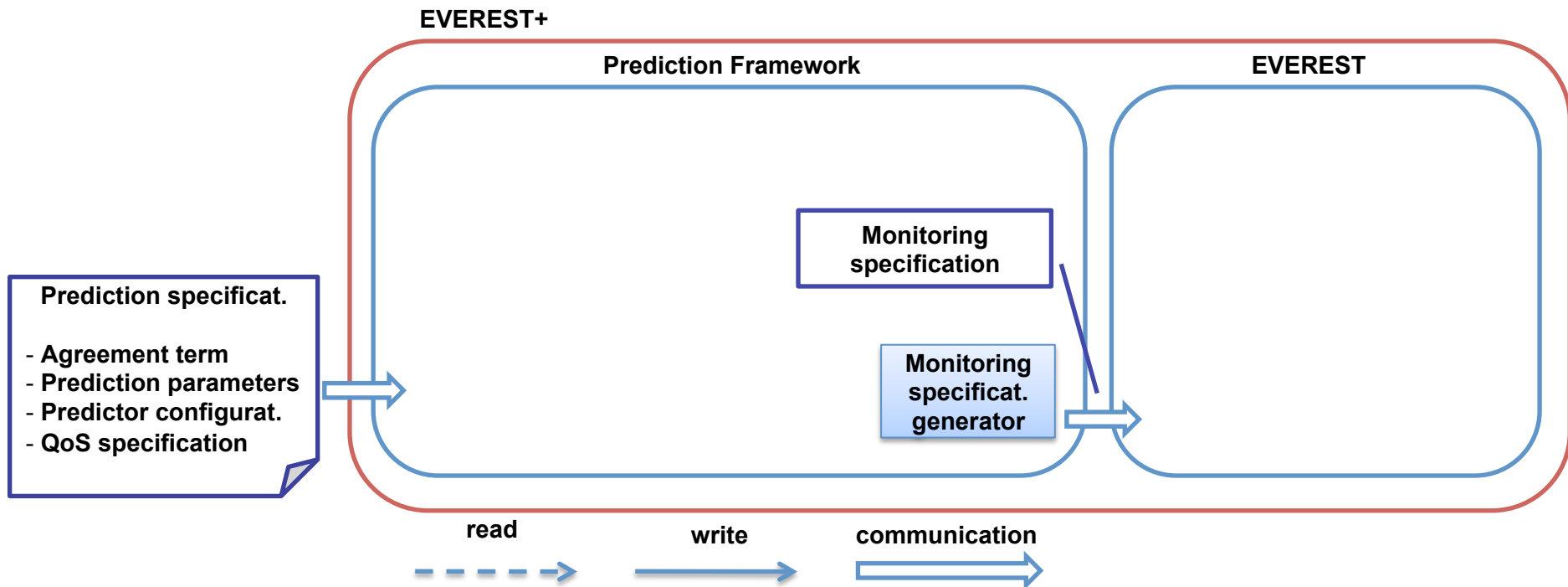
EVEREST+: architecture





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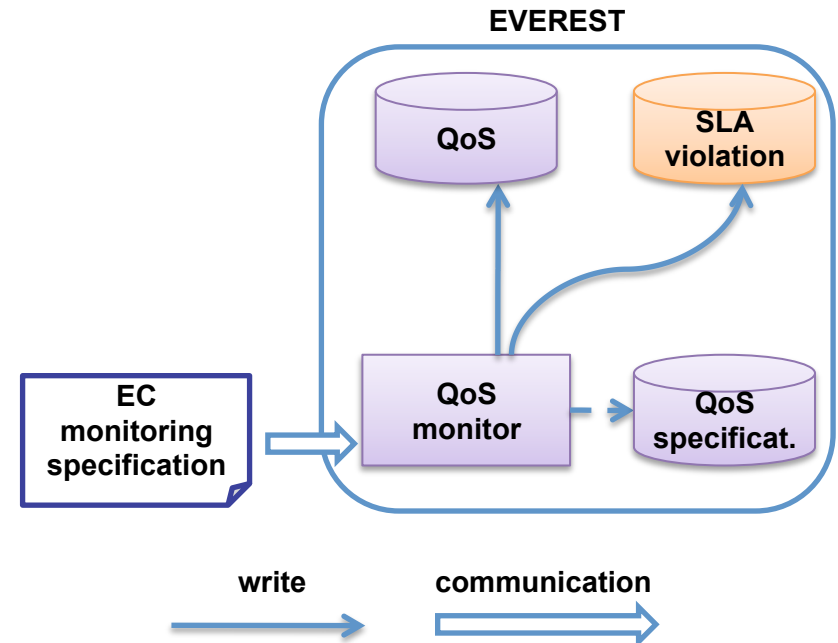
EVEREST+: architecture





EVERST+: monitoring framework EVERST

- Generic
- Based on Event Calculus (EC)
- Rules:
 - $\text{body} \Rightarrow \text{head}$
- Predicates:
 - $\text{Happens}(e, t, R(lb, ub))$
 - $\text{HoldsAt}(f, t)$
 - $\text{Initiates}(e, f, t)$
 - $\text{Terminates}(e, f, t)$
 - $\text{Initially}(f)$





EVERST+: monitoring framework EVERST

- Mean Time To Repair (MTTR) QoS: the formula checks whether the MTTR of service *_Srv* is always below a given threshold *K*, i.e., $MTTR < K$.

Rule R1:

Happens(*e*(*_id1*, *_Snd*, *_Srv*, *Call*(*_O*), *_Srv*), *t*₁, [*t*₁, *t*₁]) \wedge

Happens(*e*(*_id2*, *_Srv*, *_Snd*, *Response*(*_O*), *_Srv*), *t*₂, [*t*₁, *t*₁+*d*]) \wedge

\exists *_PN*, *_STime*, *_MTTR*: *HoldsAt*(*Unavailable*(*_PN*, *_Srv*, *_STime*), *t*₁) \wedge

HoldsAt(*MTTR*(*_Srv*, *_PN*, *_MTTR*), *t*₁)

\Rightarrow *_MTTR* < *K*



EVERST+: monitoring framework EVERST

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Rule R1:

$Happens(e(_id1, _Snd, _Srv, Call(_O), _Srv), t_1, [t_1, t_1]) \wedge$

$Happens(e(_id2, _Srv, _Snd, Response(_O), _Srv), t_2, [t_1, t_1+d]) \wedge$

$\exists _PN, _STime, _MTTR: HoldsAt(Unavailable(_PN, _Srv, _STime), t_1)) \wedge$

$HoldsAt(MTTR(_Srv, _PN, _MTTR), t_1))$

$\Rightarrow _MTTR < K$

A call to operation $_O$ of service $_Srv$ is performed at time point t_1



EVERST+: monitoring framework EVERST

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$HoldsAt(MTTR(_Srv, _PN, _MTTR), t_1))$

$\Rightarrow _MTTR < K$

A response from service $_Srv$ is received at time point t_1+d



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\exists *_PN*, *_STime*, *_MTTR*: *HoldsAt*(*Unavailable*(*_PN*, *_Srv*, *_STime*), *t*₁) \wedge

HoldsAt(*MTTR*(*_Srv*, *_PN*, *_MTTR*), *t*₁)

\Rightarrow *_MTTR* < *K*

Checks whether an operation call happened at the the time when the service has been unavailable



EVERST+: monitoring framework EVERST

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Rule R1:

Happens(e_id1 , $_Snd$, $_Srv$, *Call*($_O$), $_Srv$)

Happens(e_id2 , $_Srv$, $_Snd$, *Response*($_O$), $_Srv$)

$\exists _PN, _STime, _MTTR$: *HoldsAt*(*Unavailable*($_PN$, $_Srv$, $_STime$), t_1)

HoldsAt(*MTTR*($_Srv$, $_PN$, $_MTTR$), t_1)

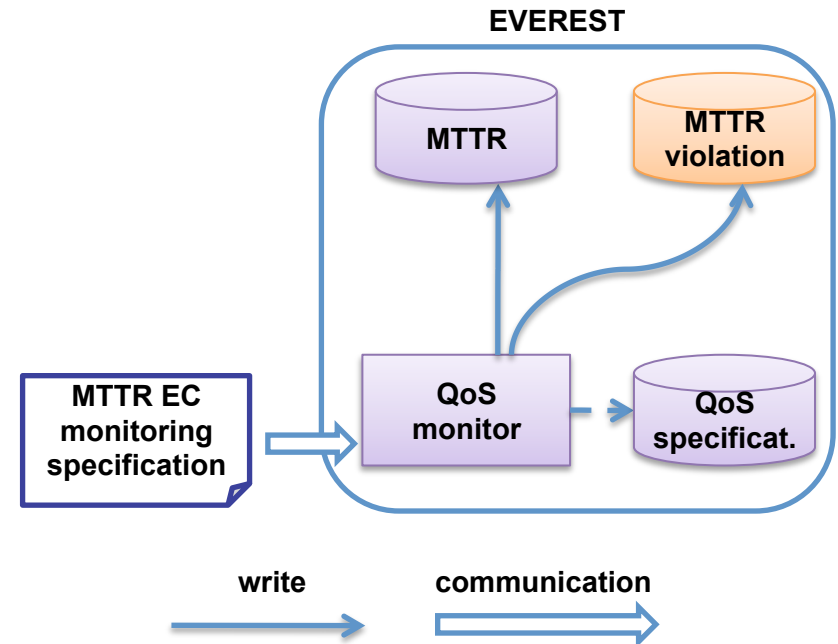
$\Rightarrow _MTTR < K$

Checks for MTTR violations ($MTTR \geq K$) when a call to an operation $_O$ of the service $_Srv$ is served after a period of unavailability



EVERST+: monitoring framework EVERST

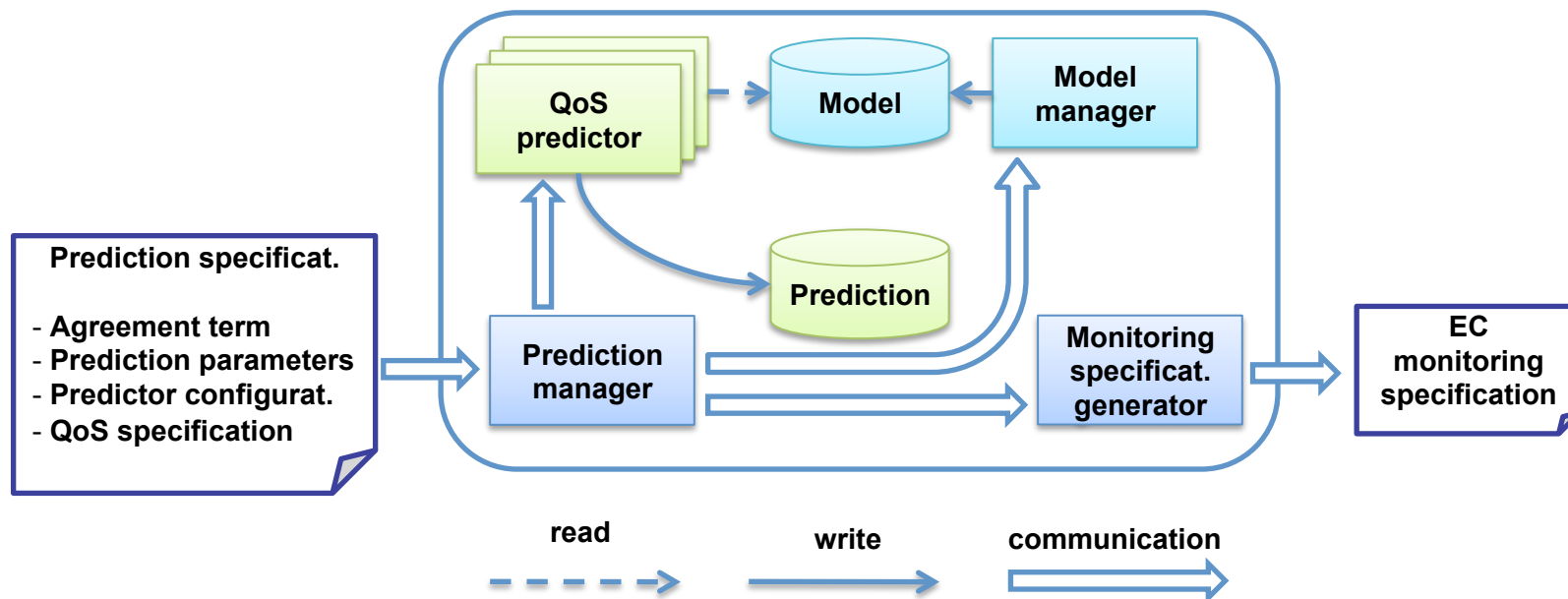
- After receiving a monitoring specification
 - computes/store MTTR values
 - checks for MTTR violations





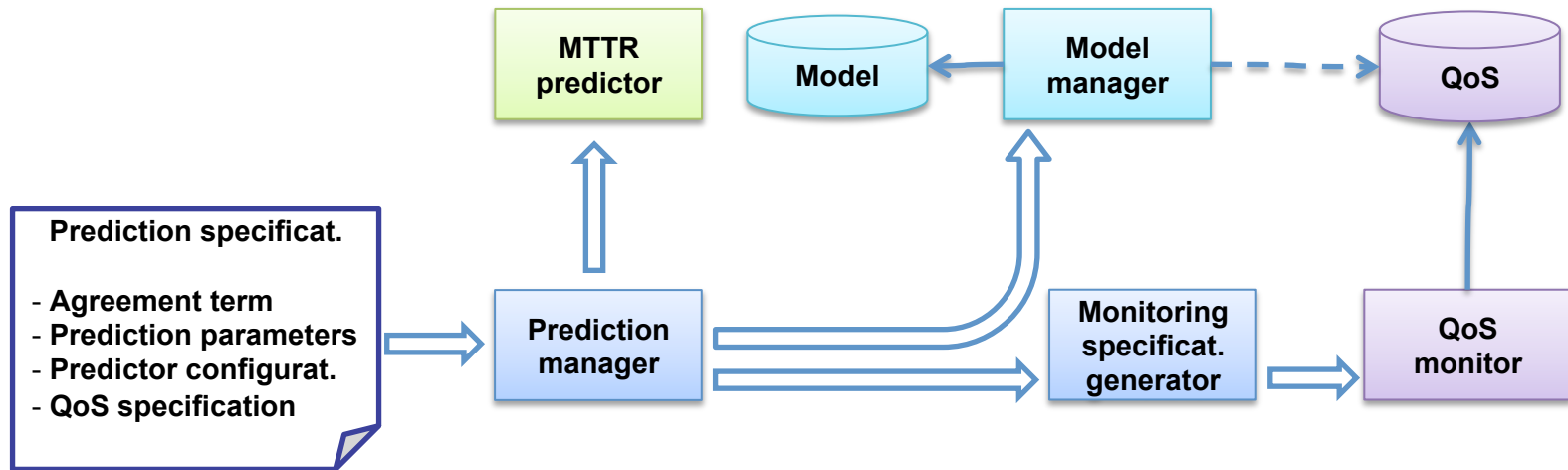
EVEREST+: prediction framework

Prediction Framework



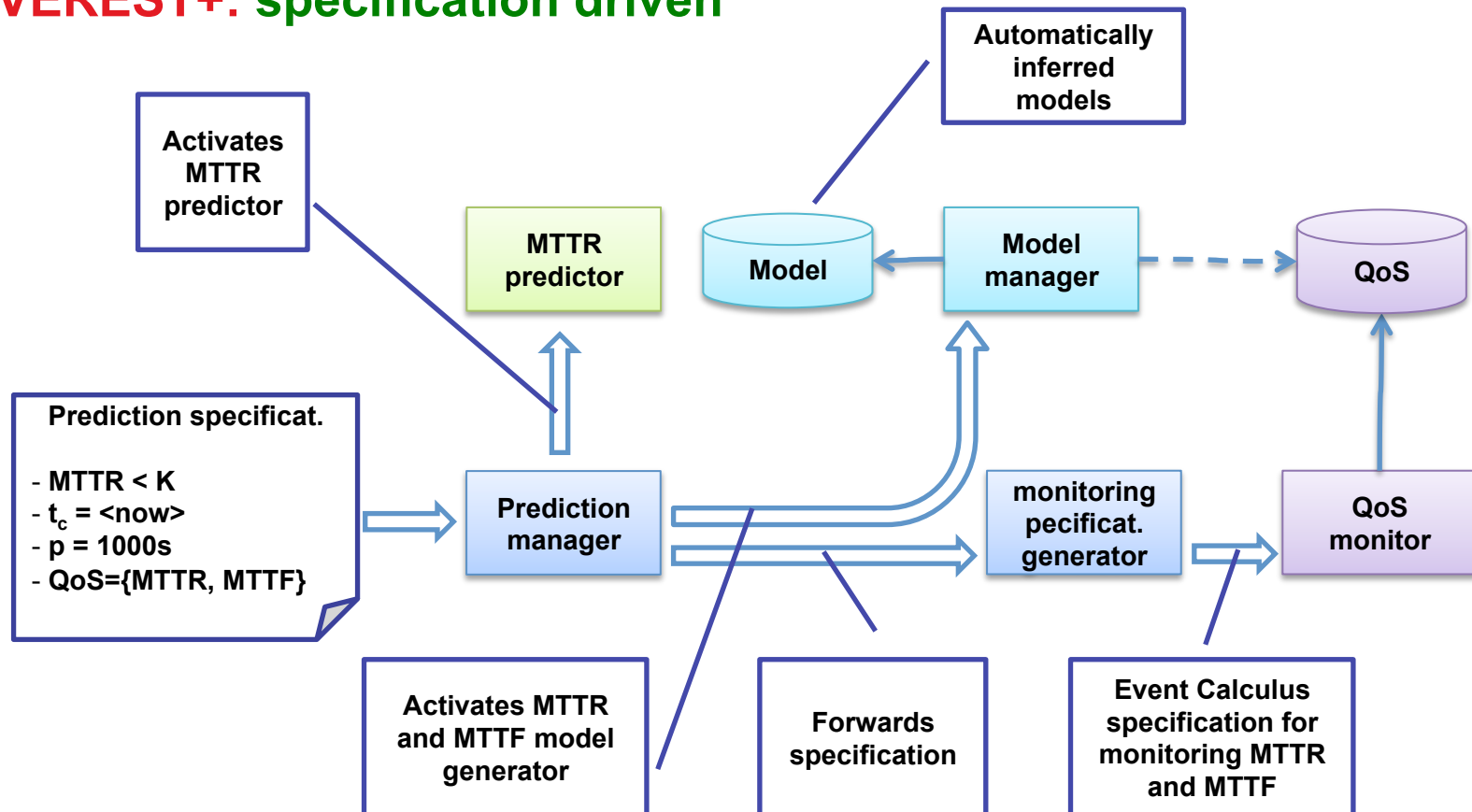


EVEREST+: specification driven





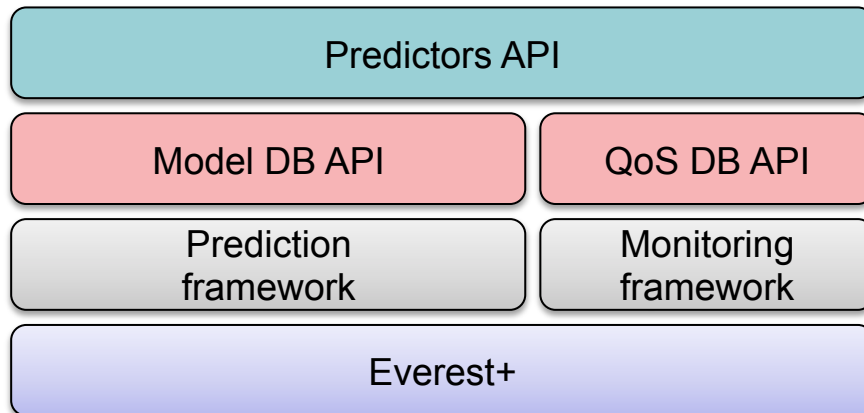
EVEREST+: specification driven





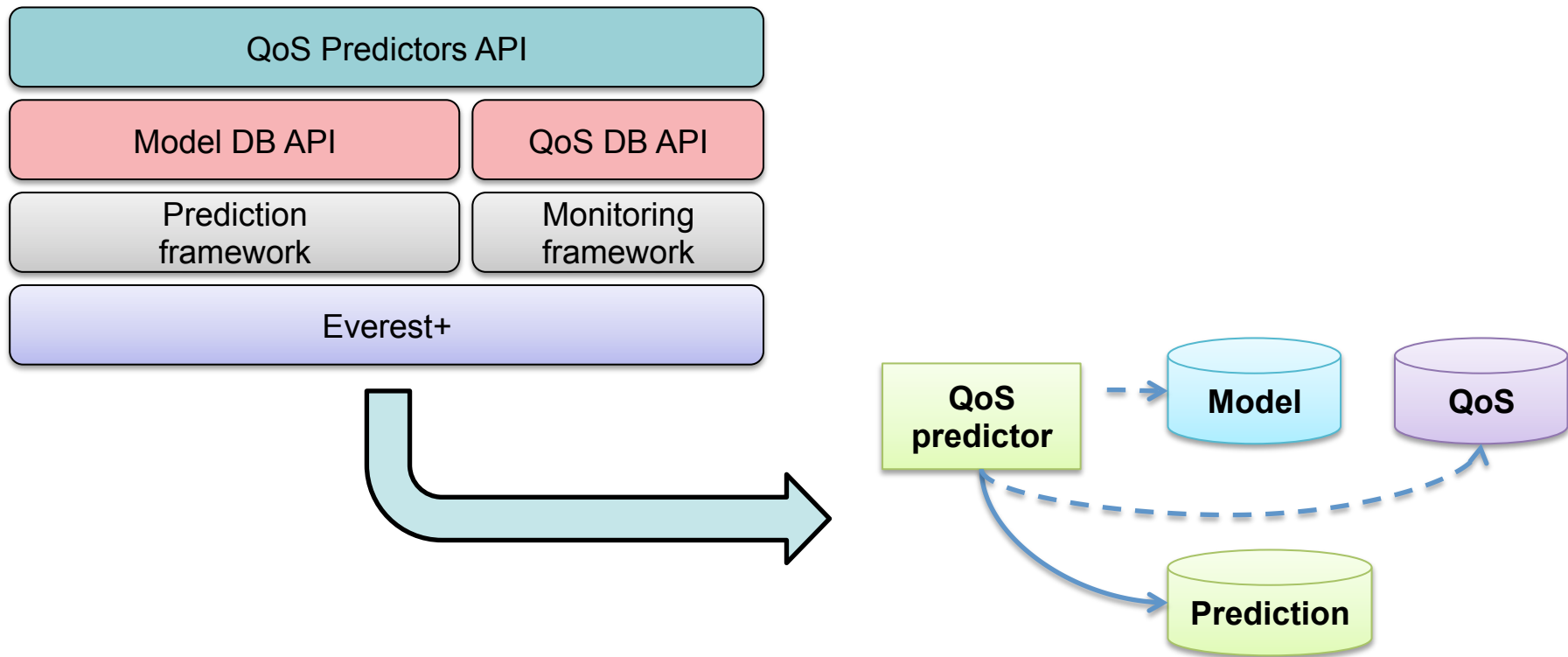
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EVEREST+: generic framework for building predictors



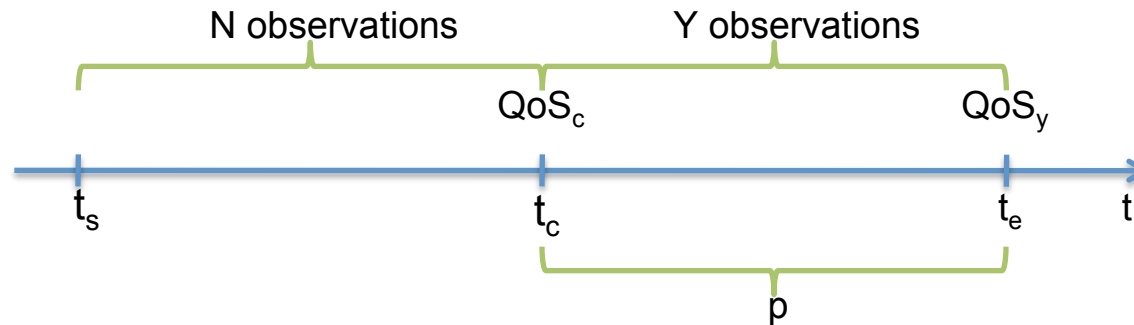


EVEREST+: generic framework for building predictors





Prediction problem



$Pr(QoS, K, t_e)$:

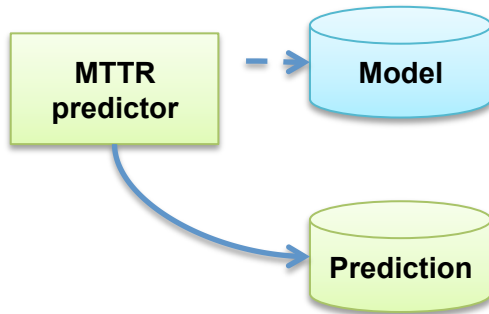
Given a request for predicting whether a QoS property will violate a given constraint K set for it at some future time point t_e that is received at a time point t_c , prediction is the computation of the probability that the QoS property will violate the constraint at t_e



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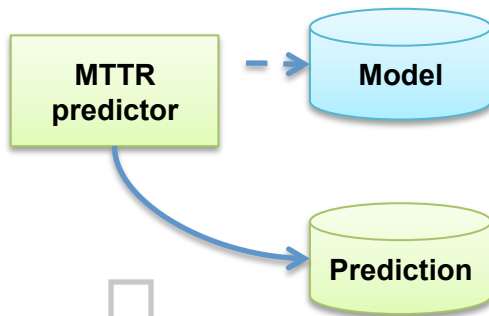
Example

EVEREST+: generic framework for building predictors





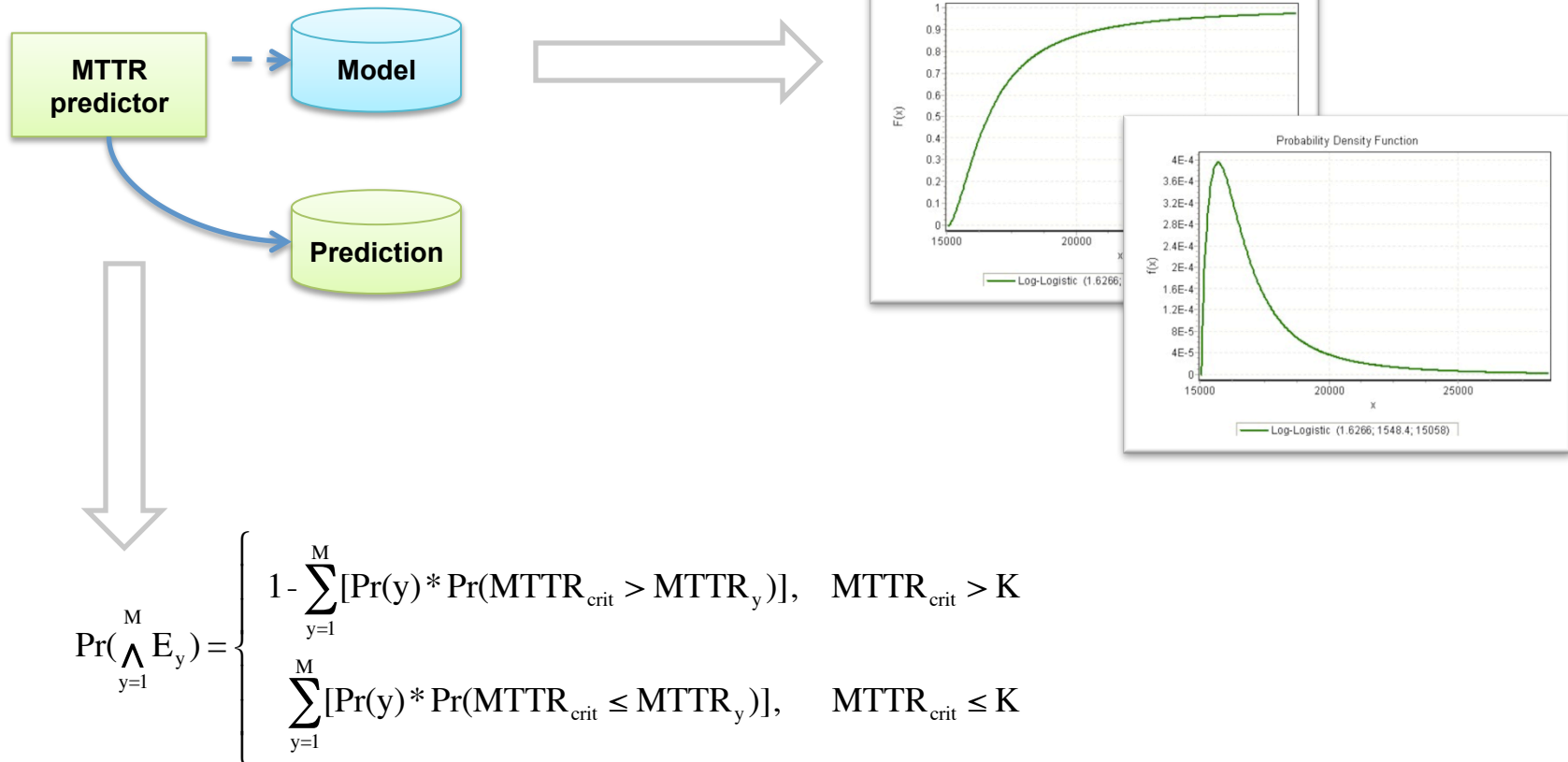
EVEREST+: generic framework for building predictors



$$\Pr(\bigwedge_{y=1}^M E_y) = \begin{cases} 1 - \sum_{y=1}^M [\Pr(y) * \Pr(\text{MTTR}_{\text{crit}} > \text{MTTR}_y)], & \text{MTTR}_{\text{crit}} > K \\ \sum_{y=1}^M [\Pr(y) * \Pr(\text{MTTR}_{\text{crit}} \leq \text{MTTR}_y)], & \text{MTTR}_{\text{crit}} \leq K \end{cases}$$



EVEREST+: generic framework for building predictors





Experimental results

- 4 MTTR Trends:
 - *T1: cyclic*
 - *T2: increasing*
 - *T3: decreasing*
 - *T4: random*
- 3 Variables:
 - History size
 - Prediction window
 - Goodness of fit
- 40 prediction measures

	T1		T2		T3		T4		Overall	
	P	R	P	R	P	R	P	R	P	R
HS size										
<i>100 events</i>	.78	.98	.77	.69	.76	1.0	.81	.77	.78	.80
<i>300 events</i>	.78	.98	.77	.69	.76	1.0	.81	.77	.78	.80
<i>500 events</i>	.78	.98	.77	.69	.76	1.0	.81	.76	.78	.80
PW length										
<i>1sec</i>	.66	.91	.57	.54	.52	1.0	.68	.63	.61	.62
<i>1min</i>	.70	1.0	.75	.67	.75	1.0	.76	.73	.74	.77
<i>10mins</i>	.66	.91	.57	.54	.52	1.0	.68	.63	.61	.62
GoF										
[.0-.05]	.82	.96	.80	.71	.76	1.0	.83	.75	.78	.85
(.05-.1]	.78	.99	.77	.68	.75	1.0	.81	.78	.78	.80
(.1-.15]	.74	1.0	.75	.67	n/a	n/a	.81	.75	.79	.75
(.15-.2]	.72	1.0	n/a	n/a	n/a	n/a	.82	.76	.80	.78



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	T1	T2	T3	T4	Overall
<i>#predictions</i>	1440	1440	1440	1440	4320
<i>precision</i>	0.78	0.77	0.76	0.81	.78
<i>recall</i>	0.98	0.69	1.00	0.77	.80



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Conclusions & Future Work

- EVEREST+ is a framework for integrated monitoring and prediction
- EVEREST+ uses prediction specifications to setup both the monitoring and the prediction framework
- EVEREST+ provides the means for developing new predictors
- Testing existing predictors against data coming from different contexts
- Designing and implementation of a wider set of predictors
- Everest+ support for other monitoring frameworks





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- Lorenzoli D., Spanoudakis G.: *EVEREST+: Runtime SLA Violations Prediction*, 5th Middleware for Service-oriented Computing Workshop - in conjunction with the 11th ACM/IFIP/USENIX International Middleware Conference. Bangalore, India, 2010.
- Tsigritis T., Spanoudakis G.: *Diagnosing Runtime Violations of Security & Dependability Properties*, 20th International Conference on Software Engineering and Knowledge Engineering, 2008.





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THANK YOU

